

# Deep Learning

A (tentative) conceptual framework for deep learning from the perspective of computer science and neural networks

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*Scientific Methods II*

March 7th, 2014

## Aim of the presentation

This presentation aims at giving you a conceptual overview of the field of *deep learning* (DL) within the context of *machine learning*.

- ✓ We will deal with DL ideas, relationship between ideas and development of ideas.
- ✗ We will avoid maths and CS details, applications and excessive oversimplification.

## Reasons for being interested in deep learning

*Wide applicability:* DL may be applied to many different fields;

*Cutting edge:* DL provides state-of-art solutions to ML problems;

*Trending:* DL is the focus of interest of many companies:

- *Jun 2013:* Google acquired DNNResearch, a startup founded by G. Hinton [4]
- *Oct 2013:* Yahoo bought LookFlow to start a new DL group [6]
- *Dec 2013:* Facebook hired Y. LeCunn, head of the DL group in NYU [2]
- *Jan 2014:* Google acquired DeepMind, a DL London startup [3]
- *Feb 2014:* Netflix is deploying a GPU-based DL system on the cloud [5]

*“We have never seen machine learning or artificial intelligence technologies so quickly make an impact in industry. It’s very impressive.”*

*(Kai Yu, director of Baidu’s Institute of Deep Learning) [9]*

# Machine Learning

*What is machine learning?*

- Study of machines able to learn by themselves.
- Study of machines that can make sense of data.
- Study of machines that can learn to map inputs to outputs.

Machine learning studies algorithms that can learn meaningful functions from input to output.

# Supervised and Unsupervised Learning

What is a *meaningful* function?

- A correct mapping between an input and an expected output relying on acquired knowledge (*supervised learning* or *classification*).
- A (statistically) valid mapping between an input and an unknown output relying on the properties of the input (*unsupervised learning* or *clustering*)

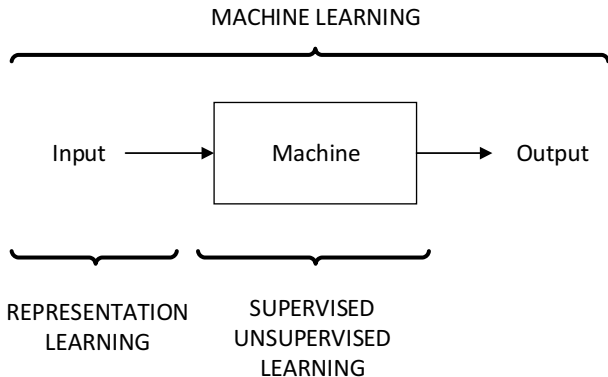
The results of learning are often dependent on having an informative input.

# Representation Learning

*How do we choose an **informative** input?*

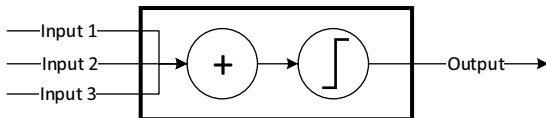
- We can extract, manually or automatically, a set of useful values from a large or noisy input (*feature extraction*).
- We can statistically transform the input in a way that highlights the information we are concerned about (*representation learning*)

# Machine Learning



# 1943 - Artificial Neuron

McCullough and Pitts introduce the model of an *artificial neuron* (AN), mimicking the activity of a spiking neuron [11].

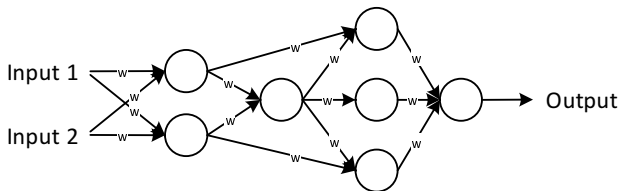


An AN is a *vector-valued thresholding function*: it receives as an input a set of values, it sums the inputs and it applies the result to a non-linear thresholding function (e.g.: sigmoid)



## 1940s - Artificial Neural Networks

Combining ANs together gives rise to an *artificial neural network* (ANN), a model resembling a brain tissue.

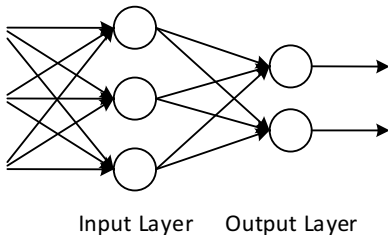


An ANN is a *weighted directed acyclic k-partite graph*; computation is performed by forwarding the inputs through the nodes of the networks and collecting its output.

Learning happens by tuning the weights.

# 1958 - Perceptrons

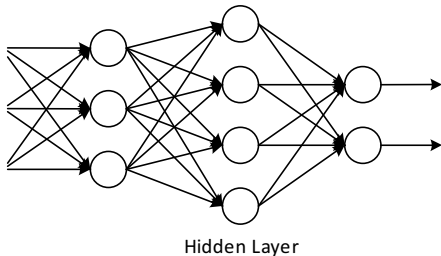
Rosenblatt defines the *perceptron*, an ANN model able to learn [12].



A perceptron is a *complete weighted directed acyclic bipartite graph*; ANs are organized into two layers, an *input layer* and an *output layer*.

## 1950s - Multi-Layer Perceptrons

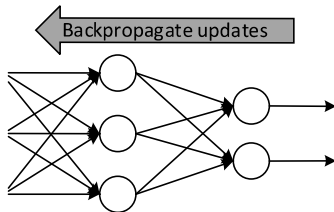
Adding layers to the original perceptron, more complex *multi-layer perceptron* (MLP) can be created.



A MLP extends a perceptron by adding a variable number of *hidden layers* between the input layer and the output layer.

## 1974 - Backpropagation Algorithm

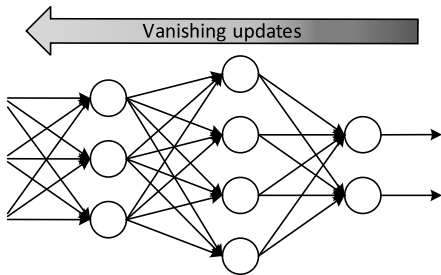
Werbos develops the *backpropagation algorithm*, an optimization technique allowing the efficient training of perceptrons [14].



The backpropagation algorithm is a variation of the *gradient descent algorithm*: it tunes a perceptron by making small changes to the weights of the network in order to make the output of a computation closer to the desired output.

## 1980s - Vanishing Gradient Problem

The training of a MLP with many hidden layers appears to suffer the problem of the *vanishing gradient* meaning that everytime information is backpropagated, part of the update is lost.



As a result, the optimization of MLPs end up stuck in *local minima* making MLPs performing poorly; MLPs were then abandoned in favour of other models, such as Support Vector Machines (SVM).

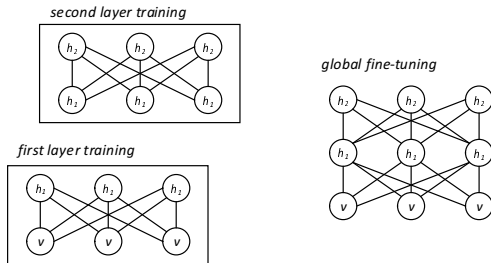
## 1989 - Universal Approximator Theorem

Cybenko proves the *universal approximator theorem* showing that a MLP can approximate any continuous function [7]

This result guarantees us that a MLP is powerful enough to approximate any continuous function (but it does not tell us how to find the best approximate function describing the relationship between a given input and a given output).

# 2006 - Deep Learning

Hinton and Salakhutdinov publish an article about *deep learning* (DL), an original way to train MLPs [10].



DL is based on the idea of a *two-stages training*:

1. An *unsupervised greedy layer-wise* training.
2. A *supervised global* fine-tuning.

# Deep Neural Networks

*Deep neural networks* (DNN) are *neural networks* made up by more than one hidden layer.

MLP with two or more hidden layers are a prototypical instance of DNN.



# Deep Learning

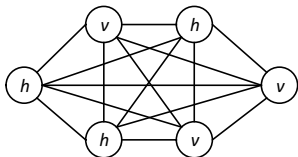
*Deep learning* (DL) is:

- A new area of machine learning [1].
- A *family of machine learning algorithms* relying on a two-stages training for tuning DNN.

Classical DL algorithms can be *Boltzmann machines*-based or *autoencoders*-based.

# Boltzmann Machine

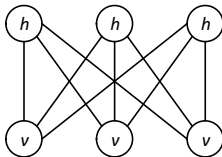
*Boltzmann machines* (BM) are a *network of symmetrically connected binary stochastic neuron-like units* [1]. BMs are not ANNs.



Units are partitioned among *visible* (v) and *hidden* (h) units. Upon receiving an input, units make stochastic decisions on their output until, in the long run, the network reaches an equilibrium given by a *Boltzmann distribution*.

# Restricted Boltzmann Machine

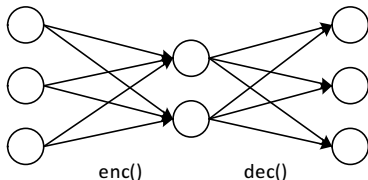
*Restricted Boltzmann machines* (RBM) are a subset of BMs with a constraint on their connections. [1].



RBMs are not allowed visible-visible or hidden-hidden connections. RBMs can be efficiently trained using the *Contrastive Divergence* algorithm.

# Autoencoders

*Autoencoders* (AE) are *shallow neural networks* designed to encode an input.



An autoencoder is described by an *encoding* (enc) and a *decoding* (dec) function. Ideally, the output of an autoencoder is as similar to the input as possible.

## Aside: A Semantic Note

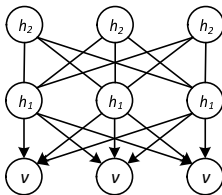
*Deep* denotes an architecture made up by several layers;

*Stacking* denotes the act of putting together several layers;

*Stacked* denotes an architecture built by stacking several layers.

# Deep Belief Networks

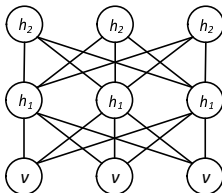
*Deep belief networks* (DBN) are directed-undirected probabilistic generative models made up by stacking RBMs (or AEs) [1]. DBNs are not ANNs.



First, each layer of a DBN is trained independently in a greedy way. Then, the DBN can undergo a global fine-tuning.

# Deep Boltzmann Machines

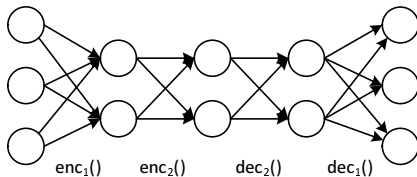
*Deep Boltzmann machines* (DBM) or *Stacked Restricted Boltzmann Machines* (SRBM) are undirected probabilistic generative models made up by stacked RBMs [13]. DBMs are not ANNs.



Differently from DBN, a DBM can propagate information in both direction during training, leading to a better approximation.

# Deep Autoencoders

*Deep Autoencoders* (DeepAE) or *Stacked Autoencoders* (SAE) are neural networks built by stacking several AEs [1].



First, each AE of a DeepAE is trained independently in a greedy way. Then, the DeepAE can undergo a global fine-tuning.



## DL strategies

The networks we described (DBN, DBM, DeepAE) can be used in two different ways [8]:

*Generative way:* the networks can be used to generate representations;

*Hybrid way:* the networks are trained and their weights are used to initialize a DNN (DBN-DNN, DBM-DNN, DeepAE-DNN).



# Thanks!

Thank you very much for listening!

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