

Jointly Learning Consistent Causal Abstractions Over Multiple Interventional Distributions

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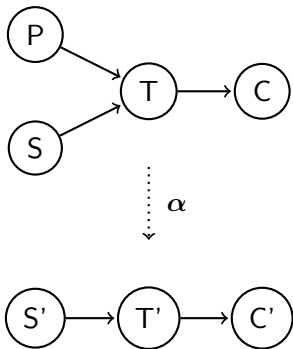
University of Warwick

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Learning Abstractions

Given two SCMs [2, 3] $\mathcal{M}, \mathcal{M}'$ representing the same system at different levels of detail [5, 1, 4], we want to learn an **abstraction** α between them.

- ✓ rely on multi-scale representations
- ✓ transfer data between different resolutions
- ✓ scale computational expense



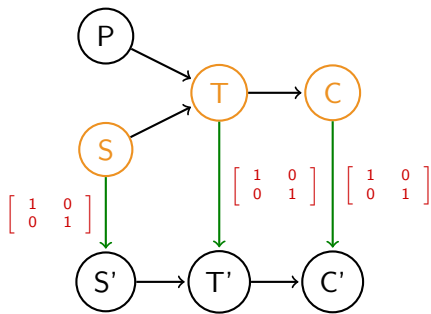
Abstraction [4]

An **abstraction** α is a tuple

$$\langle R, a, \alpha_i \rangle$$

where:

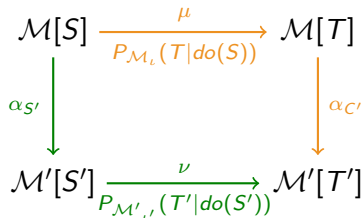
- $R \subseteq \mathcal{X}$ are relevant variables;
- $a : R \rightarrow \mathcal{X}'$ is a surjective function between *variables*;
- $\alpha_i : \mathcal{M}[a^{-1}(X'_i)] \rightarrow \mathcal{M}'[X'_i]$ is a collection of surjective functions between *outcomes*.



$$\alpha : \begin{cases} R = \{S, C, T\} \\ a(S) \mapsto S', a(T) \mapsto T', a(C) \mapsto C' \\ \alpha_{S'}(s) \mapsto s, \alpha_{T'}(t) \mapsto t, \alpha_{C'}(c) \mapsto c \end{cases}$$

Abstraction Error [4]

Given two (disjoint set of) variables in \mathcal{X}' , we evaluate **abstraction error** in terms of *interventional consistency* $E_\alpha(X', Y')$ as the maximum *distance between interventional distributions*.



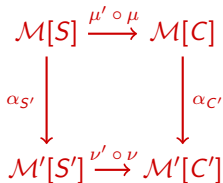
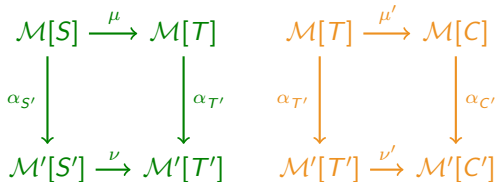
$$E_\alpha(S', T') = \max_t D_{\text{JSD}}(\alpha_{T'} \cdot \mu, \nu \cdot \alpha_{S'})$$

Abstraction Errors [4]

An abstraction implies multiple *abstraction errors*.

(Global) abstraction error

$e(\alpha)$ is the maximum abstraction error over all disjoint sets of variable.

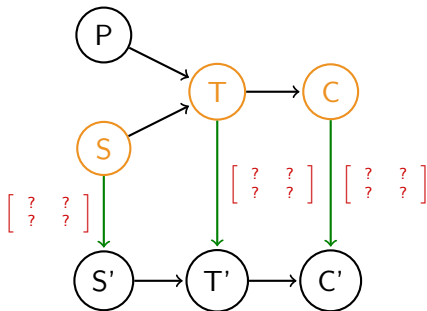


$$e(\alpha) = \sup_{\mathbf{X}', \mathbf{Y}' \subseteq \mathcal{X}'} E_{\alpha}(\mathbf{X}', \mathbf{Y}')$$

Problem statement

Given a partially define
abstraction α in terms of $\langle R, a \rangle$
can I learn α_i as:

$$\min_{\alpha} e(\alpha)$$



Challenges

(i) *Multiple related problems*

(ii) *Combinatorial optimization*

(iii) *Surjectivity constraints*

Baselines: parallel or sequential approaches.

$$\alpha_{S'} = \begin{bmatrix} ? & ? \\ ? & ? \end{bmatrix}, \alpha_{T'} = \begin{bmatrix} ? & ? \\ ? & ? \end{bmatrix}, \alpha_{C'} = \begin{bmatrix} ? & ? \\ ? & ? \end{bmatrix}$$

$$\begin{array}{ccc} \mathcal{M}[S] & \xrightarrow{\mu} & \mathcal{M}[T] & & \mathcal{M}[T] & \xrightarrow{\mu'} & \mathcal{M}[C] \\ \alpha_{S'} \downarrow & & \alpha_{T'} \downarrow & & \alpha_{T'} \downarrow & & \alpha_{C'} \downarrow \\ \mathcal{M}'[S'] & \xrightarrow{\nu} & \mathcal{M}'[T'] & & \mathcal{M}'[T'] & \xrightarrow{\nu'} & \mathcal{M}'[C'] \end{array}$$

$$\begin{array}{ccc} \mathcal{M}[S] & \xrightarrow{\mu' \circ \mu} & \mathcal{M}[C] \\ \alpha_{S'} \downarrow & & \alpha_{C'} \downarrow \\ \mathcal{M}'[S'] & \xrightarrow{\nu' \circ \nu} & \mathcal{M}'[C'] \end{array}$$

Relaxation and parametrization

We address (ii) *combinatorial optimization* by *relaxing* and *parametrizing* all α_j .

$$\min_{\alpha(\mathbf{W})} e(\alpha(\mathbf{W}))$$

$$\alpha_{S'}, \alpha_{T'}, \alpha_{C'} \in \mathbb{R}^{2 \times 2}$$

$$\begin{bmatrix} 0.7 & 1.2 \\ -0.2 & 3.3 \end{bmatrix}$$

We add *tempering* $t(W) = \frac{e^{\frac{w_{ij}}{T}}}{\sum_i e^{\frac{w_{ij}}{T}}}$ along the matrix columns to binarize them.

$$\alpha_{S'}, \alpha_{T'}, \alpha_{C'} \in [0, 1]^{2 \times 2}$$

$$\mathcal{L}_1 : \min_{\alpha(\mathbf{W})} e(\alpha(t(\mathbf{W})))$$

$$t \left(\begin{bmatrix} 0.7 & 1.2 \\ -0.2 & 3.3 \end{bmatrix} \right) = \begin{bmatrix} 0.99 & 0.02 \\ 0.01 & 0.98 \end{bmatrix}$$

Enforcing surjectivity

We address (iii) *surjective constraints* through a *penalty function*:

$$\mathcal{L}_2 : \min_{\mathbf{W}} \sum_{\mathbf{W}} \sum_i \left(1 - \max_j t(\mathbf{W})_{ij} \right)$$

$$\alpha_{S'}, \alpha_{T'}, \alpha_{C'} \in [0, 1]^{2 \times 2}$$

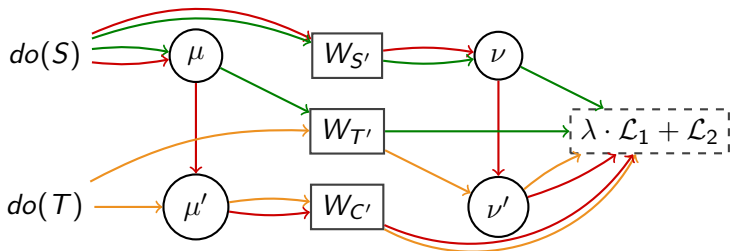
$$\begin{bmatrix} 0.99 & 0.02 \\ 0.01 & 0.98 \end{bmatrix} \overset{\mathcal{L}_2}{\rightsquigarrow}$$

$(1-0.99)+(1-0.98)$

Solution by gradient descent

We address (i) multiple related problems by *jointly* solving all the problems via *gradient descent*:

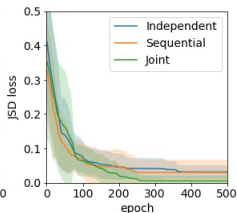
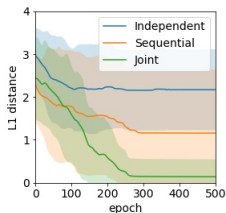
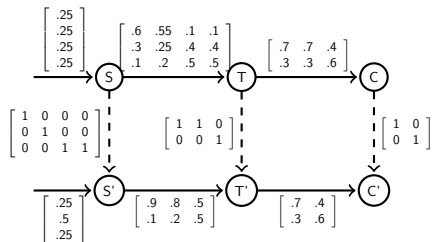
$$\begin{array}{ccc}
 \mathcal{M}[S] \xrightarrow{\mu} \mathcal{M}[T] & \mathcal{M}[T] \xrightarrow{\mu'} \mathcal{M}[C] & \mathcal{M}[S] \xrightarrow{\mu' \circ \mu} \mathcal{M}[C] \\
 \alpha_{S'} \downarrow & \alpha_{T'} \downarrow & \alpha_{S'} \downarrow \\
 \mathcal{M}'[S'] \xrightarrow{\nu} \mathcal{M}'[T'] & \mathcal{M}'[T'] \xrightarrow{\nu'} \mathcal{M}'[C'] & \mathcal{M}'[S'] \xrightarrow{\nu' \circ \nu} \mathcal{M}'[C'] \\
 \alpha_{T'} \downarrow & \alpha_{C'} \downarrow & \alpha_{C'} \downarrow
 \end{array}$$



Synthetic Experiments

We evaluated our learning method:

- On multiple synthetic models;
- Against *independent* and *sequential* approach;
- Monitoring *loss functions*, *L1-dist from ground truth*, *wall-clock time*.



Real-World Experiments

We evaluated our learning methods:

- On battery manufacturing data collected by two research groups (LRCS, WMG) using different model;
- Performing abstraction of data from base to abstracted (WMG \rightarrow LRCS);
- Evaluating change in performance using aggregated data when predicting out-of-sample (k).

	Training set	Test Set	MSE
(a)	LRCS[$CG \neq k$]	LRCS[$CG = k$]	1.86 ± 1.75
(b)	LRCS[$CG \neq k$] + WMG	LRCS[$CG = k$]	0.22 ± 0.26
(c)	LRCS[$CG \neq k$] + WMG[$CG \neq k$]	LRCS[$CG = k$] + WMG[$CG = k$]	1.22 ± 0.95

Thanks!

Thank you for listening!

References I

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- [5] Paul K Rubenstein, Sebastian Weichwald, Stephan Bongers, Joris M Mooij, Dominik Janzing, Moritz Grosse-Wentrup, and Bernhard Schölkopf. Causal consistency of structural equation models. In *33rd Conference on Uncertainty in Artificial Intelligence (UAI 2017)*, pages 808–817. Curran Associates, Inc., 2017.